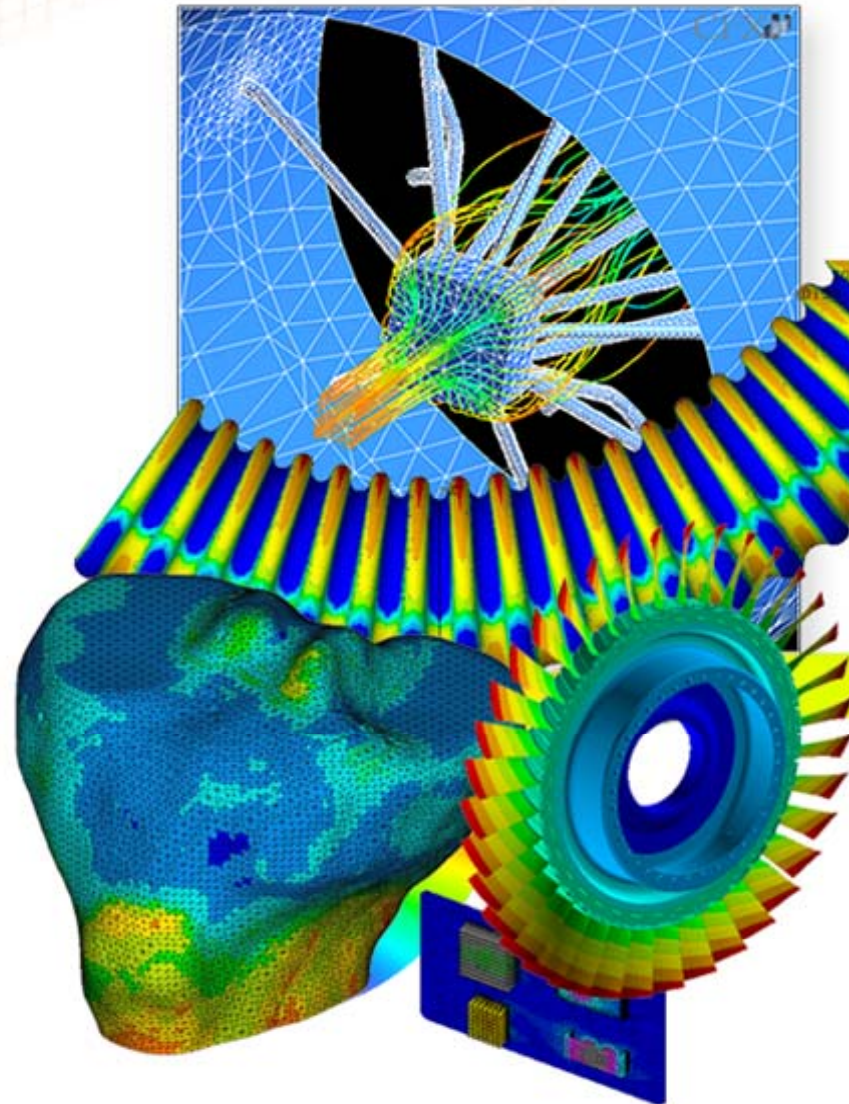


# Damping in ANSYS/LS-Dyna

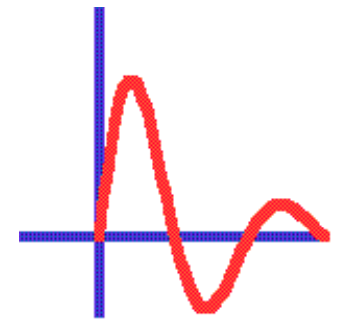
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- ANSYS/LS-Dyna allows Rayleigh damping constants  $\alpha$  and  $\beta$  only.

## What is damping?

- The energy dissipation mechanism that causes vibrations to diminish over time and eventually stop.
- Amount of damping mainly depends on the material, velocity of motion, and frequency of vibration.
- Can be classified as:
  - Viscous damping
    - Damping ratio  $\xi$
    - Rayleigh mass-weighted damping constant  $\alpha$
  - Hysteresis or solid damping
    - Rayleigh stiffness-weighted damping constant  $\beta$



- Most damping in an ANSYS dynamics analysis is approximated as some form of viscous damping:

$$F = C\dot{x}$$

- The proportionality constant  $c$  is called the *damping constant*.
- The amount of damping is usually described using a quantity called the *damping ratio*  $\xi$  (ratio of damping constant  $c$  to critical damping constant  $c_c^*$ ).
- Critical damping is defined as the threshold between oscillatory and non-oscillatory behavior, where damping ratio = 1.0.

\*For a single-DOF spring mass system of mass  $m$  and frequency  $\omega$ ,  $c_c = 2m\omega$

- Rayleigh damping constants  $\alpha$  and  $\beta$ 
  - Used as multipliers of  $[M]$  and  $[K]$  to calculate  $[C]$ :

$$[C] = \alpha[M] + \beta[K]$$

$$\alpha/2\omega + \beta\omega/2 = \xi$$

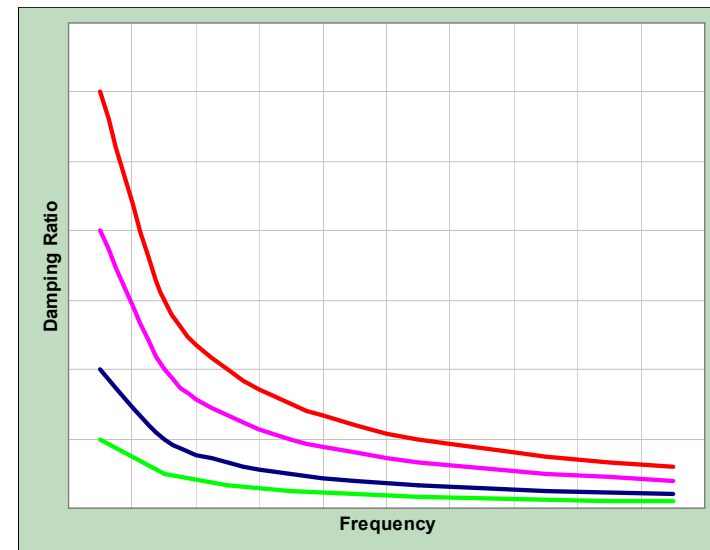
- Where  $\omega$  is the frequency, and  $\xi$  is the damping ratio.
- Needed in situations where damping ratio  $\xi$  cannot be specified.
- Alpha is the viscous damping component, and Beta is the hysteresis or solid or *stiffness* damping component.

## Alpha Damping

- Also known as *mass damping*.
- Good for damping out low-frequency system-level oscillations (typically high amplitude).
- If beta damping is ignored,  $\alpha$  can be calculated from a known value of  $\xi$  (damping ratio) and a known frequency  $\omega$ :

$$\alpha = 2\xi\omega$$

- Only one value of alpha is allowed, so pick the most dominant response frequency to calculate  $\alpha$ .

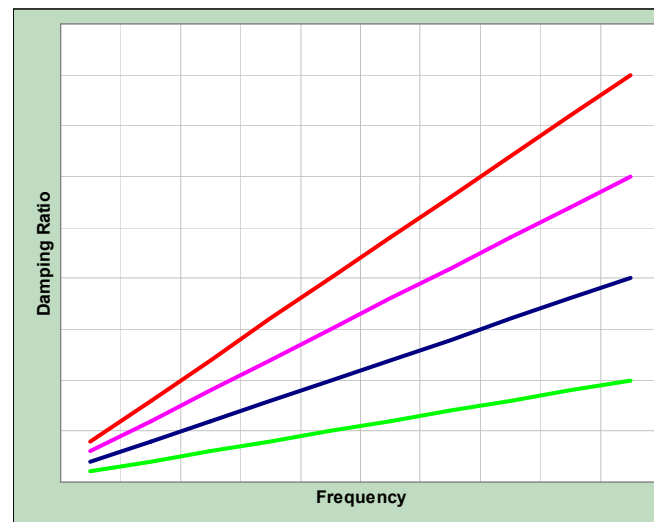


## Beta Damping

- Also known as *structural* or *stiffness* damping.
- Good for damping out high-frequency component-level oscillations (typically low amplitude).
- Inherent property of most materials.
- If alpha damping is ignored,  $\beta$  can be calculated from a known value of  $\xi$  (damping ratio) and a known frequency  $\omega$ :

$$\beta = 2\xi/\omega$$

- Pick the most dominant response frequency to calculate  $\beta$ .



## To specify both $\alpha$ and $\beta$ damping:

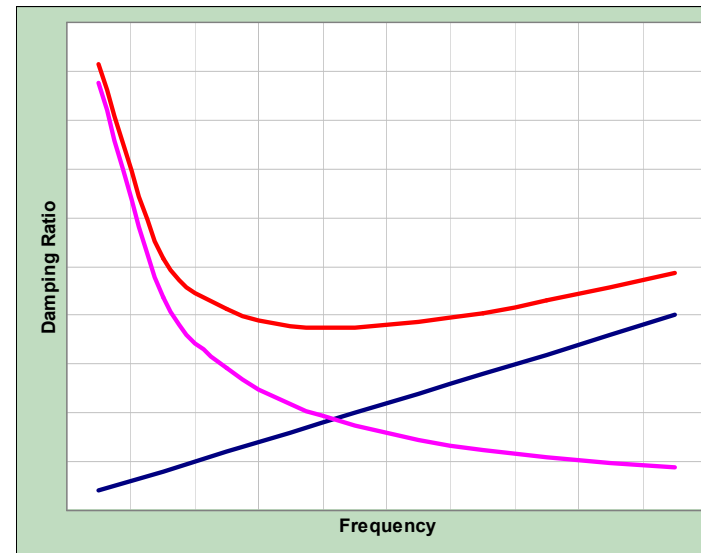
- Use the relation

$$\alpha/2\omega + \beta\omega/2 = \xi$$

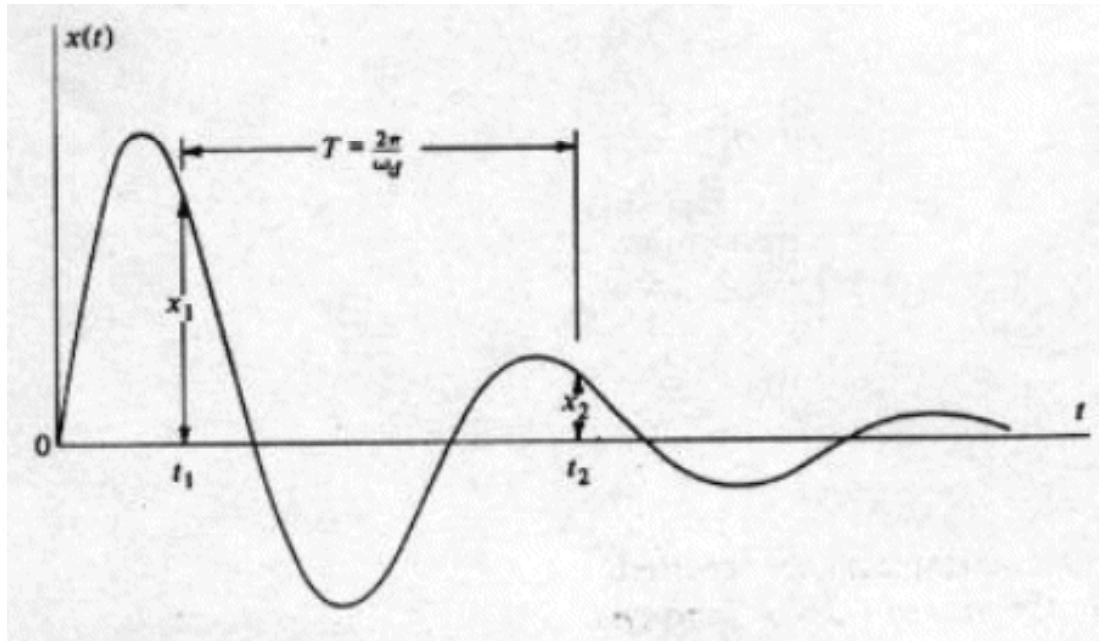
- Since there are two unknowns, assume that the sum of alpha and beta damping gives a constant damping ratio  $\xi$  over the frequency range  $\omega_1$  to  $\omega_2$ . This gives two simultaneous equations from which you can solve for  $\alpha$  and  $\beta$ .

$$\xi = \alpha/2\omega_1 + \beta\omega_1/2$$

$$\xi = \alpha/2\omega_2 + \beta\omega_2/2$$



- The damping ratio,  $\xi$ , can be obtained from test data as follows



- Calculate the logarithmic decrement,  $\delta$ , as follows:

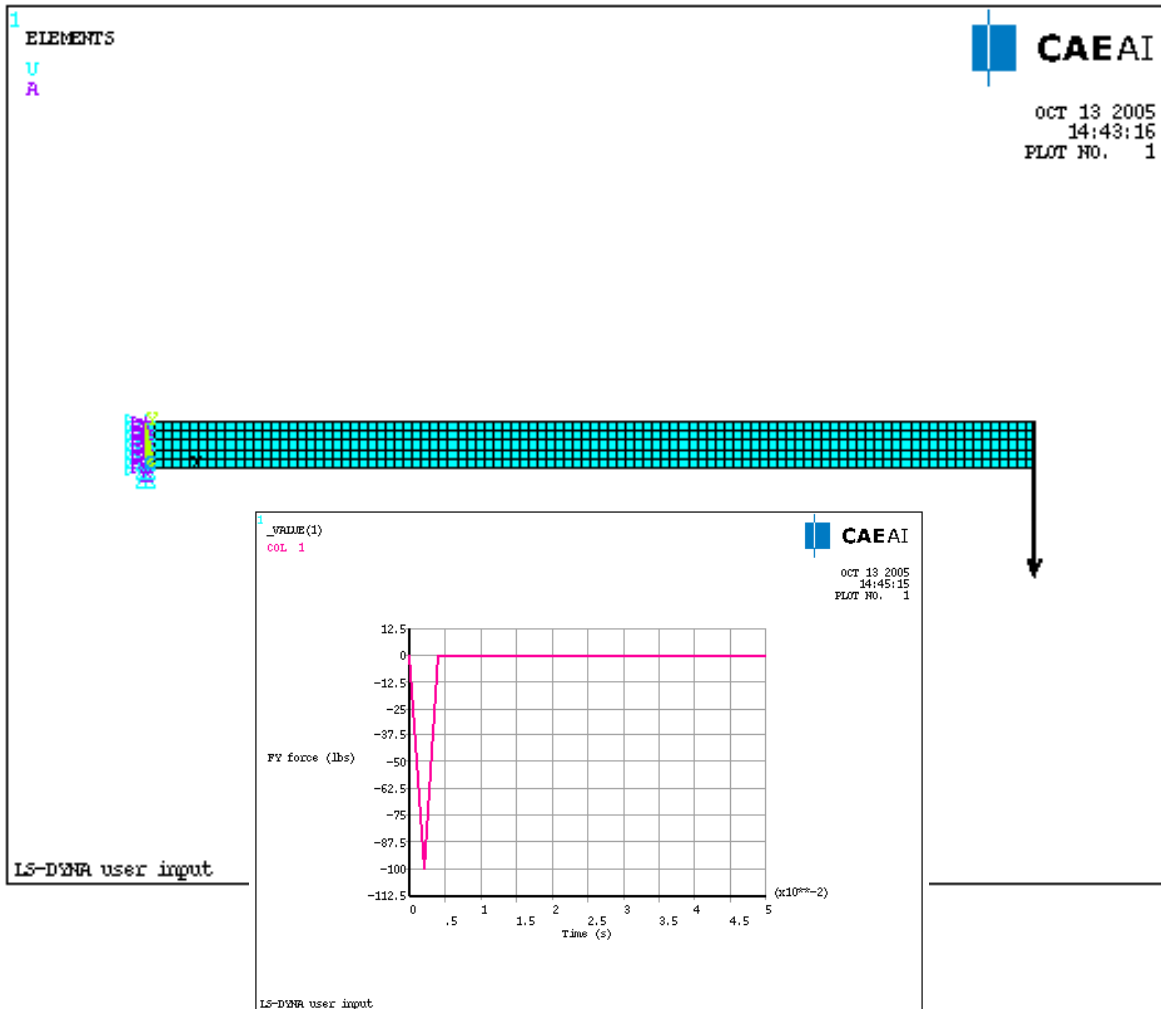
$$\delta = \ln(x_1/x_2)$$

- $x_1$  and  $x_2$  are two consecutive displacements, one cycle apart.

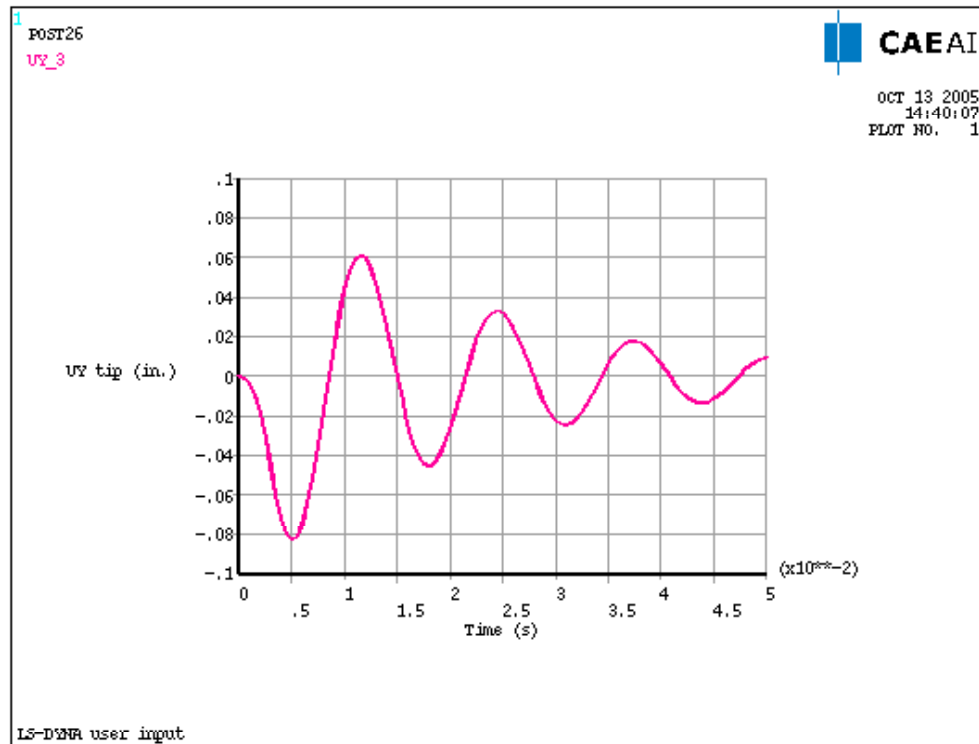


$$\zeta = \frac{\delta}{\sqrt{(2\pi)^2 + \delta^2}}$$

- Cantilever beam with an impulse load applied to the tip

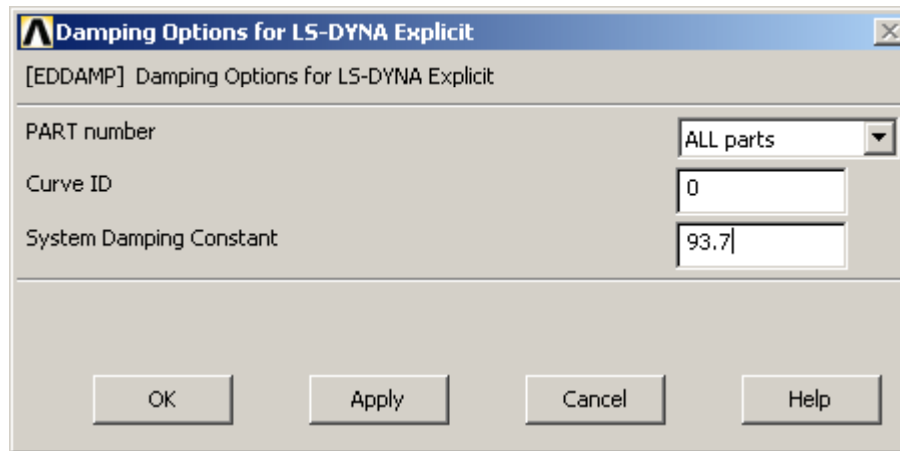


- Tip deflection:  $\omega = 76.9 \text{ cycles/s} = 483 \text{ rad/s}$

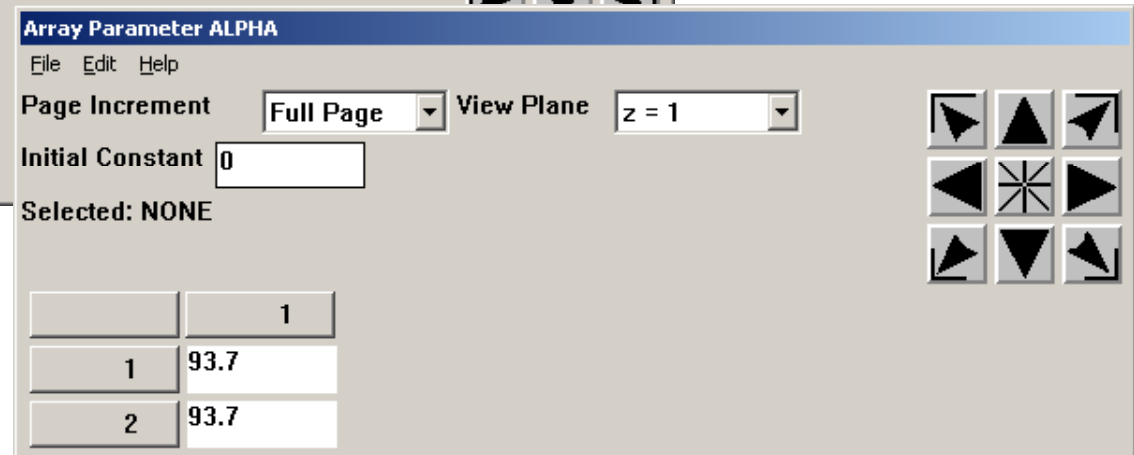
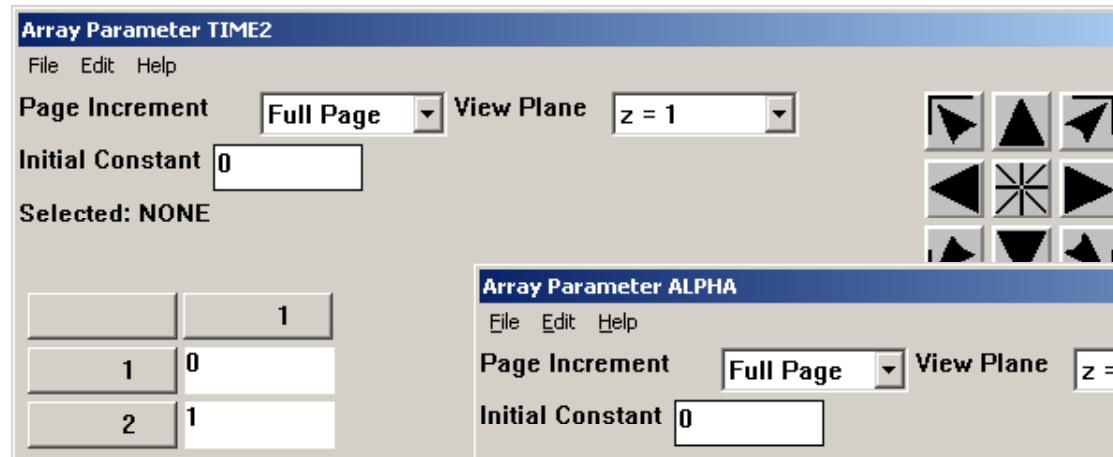


- $\delta = \ln(0.061/0.033) = 0.614$
- $\xi = 0.097$
- $\alpha = 2\xi\omega = 93.7 \text{ s}^{-1}$  **or**  $\beta = 2\xi/\omega = 0.0004 \text{ s}$

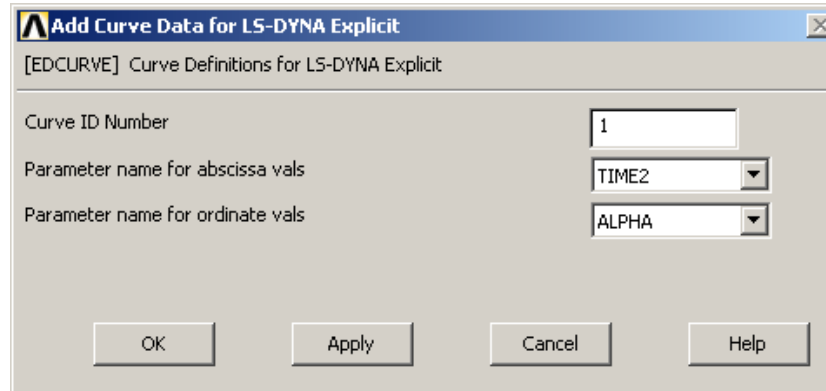
- Alpha damping
  - Same alpha damping applied to all parts
    - Preprocessor > Material Props > Damping
    - Set the part number to All parts and do not specify a curve ID



- Alpha damping
  - Time-varying alpha damping applied to a specific part
    - Create a curve ID for alpha damping vs. time and identify it in the damping input window.
    - Utility Menu > Parameters > Array Parameters > Define/Edit
    - Dimension and fill the time and alpha vectors



- Generate a curve that relates the alpha to time
  - Preprocessor > LS-Dyna Options > Loading Options > Curve Options > Add Curve

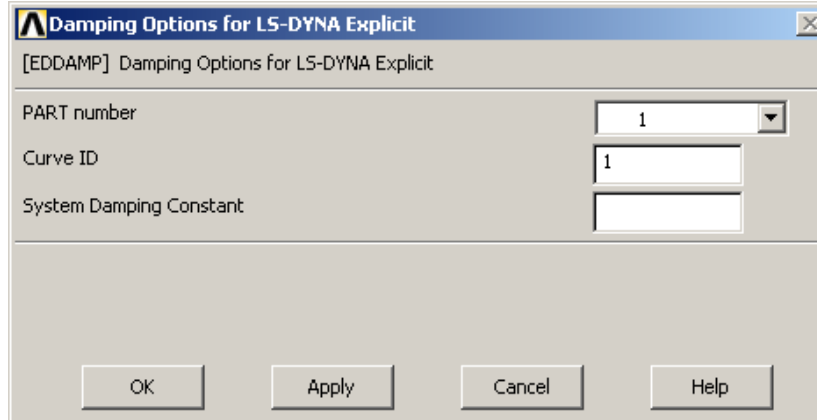


The dialog box is titled "Add Curve Data for LS-DYNA Explicit" and contains the following fields:

- Curve ID Number: 1
- Parameter name for abscissa vals: TIME2
- Parameter name for ordinate vals: ALPHA

Buttons: OK, Apply, Cancel, Help

- Assign the curve to the appropriate part
  - Preprocessor > Material Props > Damping



The dialog box is titled "Damping Options for LS-DYNA Explicit" and contains the following fields:

- PART number: 1
- Curve ID: 1
- System Damping Constant: (empty)

Buttons: OK, Apply, Cancel, Help

- Beta damping
  - Constant beta damping applied to a specific part
    - Preprocessor > Material Props > Damping
    - Use a specific part number and do not specify a curve ID

